4. Conclusions

As a result of the literature reviews we compare the four types of actuators according to their material that are used in the actuator body, additional material that are used in application, number of production steps, the number of equipments, reproducibility and actuator functions.

All of the soft robots are produced by soft materials but there isn't any system which is completely soft. In all systems even if actuators can be completely soft, but all additional components are rigid.

Pneunet bending actuators is the most reproducible actuators , but they have minimum functionality. According to production steps, generally an actuator which has more steps has more function seems.

The most determinative topics for usage of the actuator are reproducibility and functions. According to these topics the most useful actuator type is fiber reinforced. This type of actuators have three types functions and also combine of these functions and one advantage of these type of actuator is not requiring any assist component.

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